

4. The method as set forth in claim 1, wherein an implant may be selected as a data model from a plurality of data models.

5. The method as set forth in claim 1, wherein said implant is virtually positioned relative to said body.

6. The method as set forth in claim 1, wherein a desired position of said element to be applied is determined from the position of said implant.

7. The method as set forth in claim 1, wherein the position of connecting points between body and element is determined from the position of said element.

8. The method as set forth in claim 1, wherein aligning said body and/or calibrating said device for preparing and/or producing a connection is implemented.

9. The method as set forth in claim 1, wherein a connection is prepared or produced at determined connecting points.

14. The system as set forth in claim 12, wherein said position detection device detects optical, acoustical and/or radio signals.

15. The system as set forth in claim 12, wherein one or more markers are applied to said element and/or said body.

16. The system as set forth in claim 12, wherein a processor is provided for preparing or implementing one or more of the steps in a method comprising: detecting the position of a device for preparing and/or producing a connection between said body and said element relative to the position of said body.

17. The system as set forth in claim 12, wherein a display device is provided, connected to said processor.